

AMENDMENTS TO THE CLAIMS

The following listing of claims will replace all prior versions, and listings, of claims in this application.

1. (Original) A method of denoising signal mixtures so as to extract a signal of interest, the method comprising:

receiving a pair of signal mixtures;
constructing a time-frequency representation of each mixture;
constructing a pair of histograms, one for signal-of-interest segments, the other for non-signal-of-interest segments;
combining said histograms to create a weighting matrix;
rescaling each time-frequency component of each mixture using said weighting matrix; and
resynthesizing the denoised signal from the reweighted time-frequency representations.

2. (Original) The method of claim 1 wherein said receiving of mixing signals utilizes signal-of-interest activation.

3. (Original) The method of claim 2 wherein said signal-of-interest activation detection is voice activation detection.

4. (Original) The method of claim 1 wherein said histograms are a function of amplitude versus a function of relative time delay.

5. (Original) The method of claim 1 wherein said combining of histograms to create a weighting matrix comprises:

subtracting said non-signal-of-interest segment histograms from said signal-of-interest segment histogram so as to create a difference histogram; and rescaling said difference histogram to create a weighting matrix.

6. (Currently Amended) The method of claim 5 wherein said rescaling of said difference histogram to create the weighting matrix comprises rescaling said difference histogram with a rescaling function $f(x)$ that maps x to $[0,1]$.

7. (Currently Amended) The method of claim 6 wherein said rescaling function $f(x)$ is given by the equation:

$$f(x) = \begin{cases} \tanh(x), & x > 0 \\ 0, & x \leq 0 \end{cases}.$$

8. (Original) The method of claim 6 wherein said rescaling function $f(x)$ maps a largest p percent of histogram values to unity and the remaining values to zero.

9. (Original) The method of claim 5 wherein said histograms and weighting matrix are a function of amplitude versus a function of relative time delay.

10. (Currently Amended) The method of claim 1 wherein said constructing of a time-frequency representation of each mixture is given by the equation:

$$\begin{bmatrix} X_1(\omega, \tau) \\ X_2(\omega, \tau) \end{bmatrix} = \begin{bmatrix} 1 & \dots & 1 \\ a_1 e^{-i\omega\delta_1} & \dots & a_N e^{-i\omega\delta_N} \end{bmatrix} \begin{bmatrix} S_1(\omega, \tau) \\ \vdots \\ S_N(\omega, \tau) \end{bmatrix} + \begin{bmatrix} N_1(\omega, \tau) \\ N_2(\omega, \tau) \end{bmatrix}$$

where $X(\omega, \tau)$ is the time-frequency representation of $x(t)$ constructed using the equation for said constructing of a time-frequency representation of each given mixture Equation 4, ω is the frequency variable (in both the frequency and time-frequency domains), τ is the time variable in the time-frequency domain that specifies the alignment of the window, a_i is the relative mixing parameter associated with the i^{th} source, N is the total

number of sources, $S(\omega, \tau)$ is the time-frequency representation of $s(t)$, $N_1(\omega, \tau)$ or $N_2(\omega, \tau)$ are the noise signals $n_1(t)$ and $n_2(t)$ in the time-frequency domain.

11. (Original) The method of claim 10 wherein said histograms are constructed according to an equation selected from the group:

$$H_v(m, n) = \sum_{\omega, \tau} |X_1^w(\omega, \tau)| + |X_2^w(\omega, \tau)|, \text{ and}$$

$$H_v(m, n) = \sum_{\omega, \tau} |X_1^w(\omega, \tau)| \bullet |X_2^w(\omega, \tau)|,$$

where $m = \hat{A}(\omega, \tau)$, $n = \hat{\Delta}(\omega, \tau)$; and

wherein

$$\hat{A}(\omega, \tau) = [a_{num}(\hat{a}(\omega, \tau) - a_{min}) / (a_{max} - a_{min})], \text{ and}$$

$$\hat{\Delta}(\omega, \tau) = [\delta_{num}(\hat{\delta}(\omega, \tau) - \delta_{min}) / (\delta_{max} - \delta_{min})]$$

where a_{min} , a_{max} , δ_{min} , δ_{max} are the maximum and minimum allowable amplitude and delay parameters, a_{num} , δ_{num} are the number of histogram bins to use along each axis, and $[f(x)]$ is a notation for the largest integer smaller than $f(x)$.

12. (Original) The method of claim 1 further comprising a preprocessing procedure comprising:

realigning said mixtures so as to reduce relative delays for the signal of interest;

and

rescaling said realigned mixtures to equal power.

13. (Original) The method of claim 1 further comprising a postprocessing procedure comprising a blind source separation procedure.

14. (Original) The method of claim 1 wherein said histograms are constructed in a mixing parameter ratio plane.

15. (Original) A program storage device readable by machine, tangibly embodying a program of instructions executable by the machine to perform method steps for denoising signal mixtures so as to extract a signal of interest, said method steps comprising:

- receiving a pair of signal mixtures;
- constructing a time-frequency representation of each mixture;
- constructing a pair of histograms, one for signal-of-interest segments, the other for non-signal-of-interest segments;
- combining said histograms to create a weighting matrix;
- rescaling each time-frequency component of each mixture using said weighting matrix; and

resynthesizing the denoised signal from the reweighted time-frequency representations.

16. (Original) A system for denoising signal mixtures so as to extract a signal of interest, comprising:

- means for receiving a pair of signal mixtures;
- means for constructing a time-frequency representation of each mixture;
- means for constructing a pair of histograms, one for signal-of-interest segments, the other for non-signal-of-interest segments;
- means for combining said histograms to create a weighting matrix;

means for rescaling each time-frequency component of each mixture using said weighting matrix; and

means for resynthesizing the denoised signal from the reweighted time-frequency representations.